

Retrieval of Soil Moisture using Sliced Regression Inversion Technique

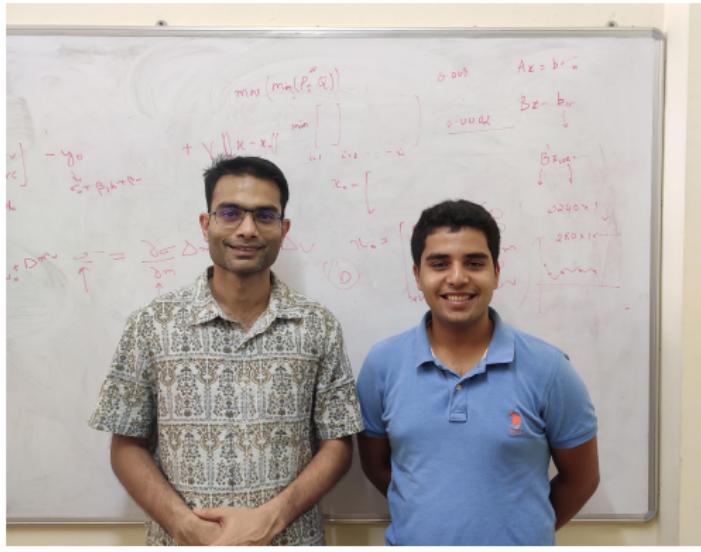
Siddhant Gautam

Sakees V Chidambaram, Niharika Gunturu, Uday K Khankhoje

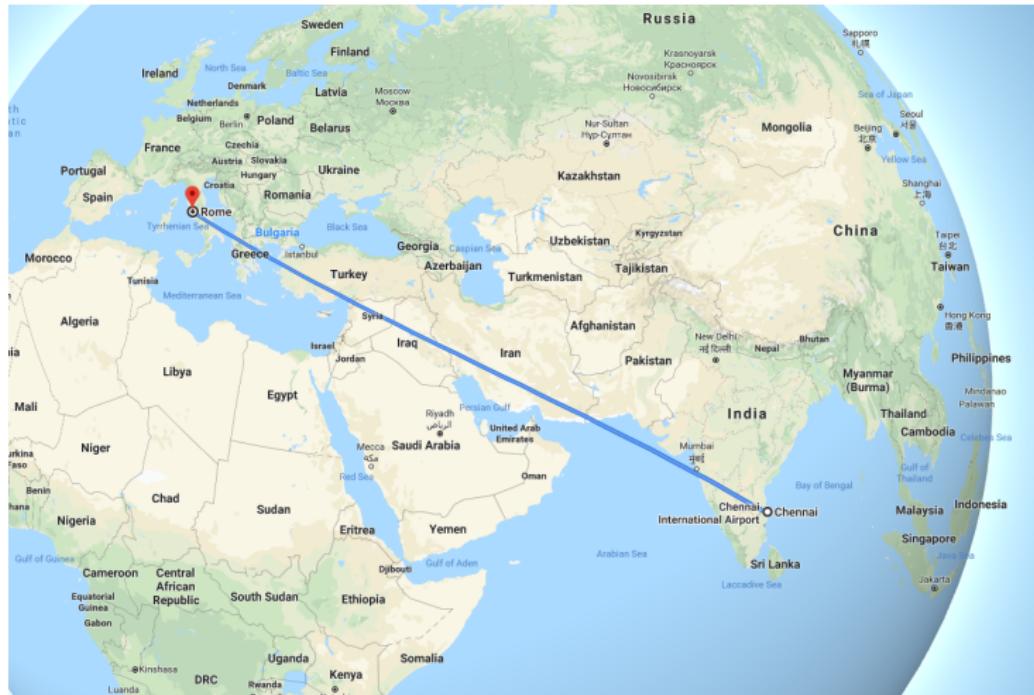
Electrical Engineering,
Indian Institute of Technology Madras

PIERS Rome, June 18, 2019

Me and my co-authors!



All roads lead to Rome!



IIT Madras - Wildlife



Soil Moisture - Why does it matter?

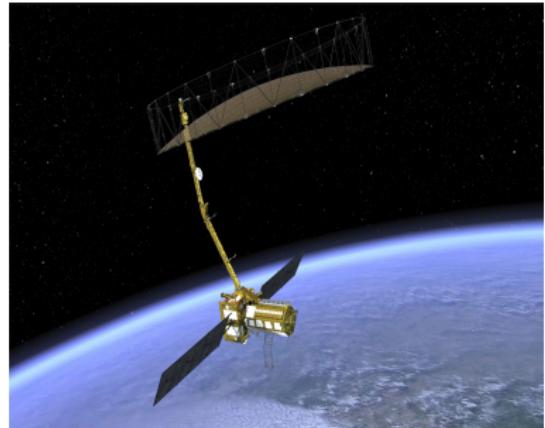


Figure: Disciplines that benefit from soil moisture measurements ¹

¹Credits : <https://smap.jpl.nasa.gov/>

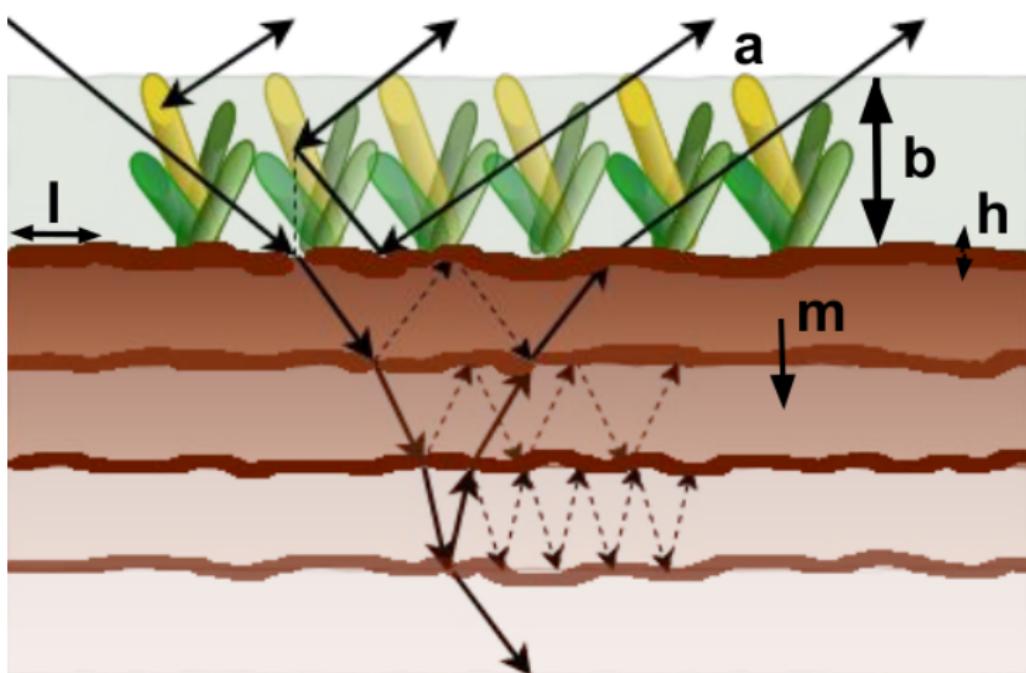
NASA-ISRO Synthetic Aperture Radar (NISAR) Mission

- Joint Mission by ISRO-NASA
- Expected Launch Date : 2021
- Operated bands : L and S
- All-Weather Day and Night Imaging
- Airborne SAR operated by ISRO
- Applications:
 - ① Agricultural Monitoring
 - ② Glacier and coastal studies
 - ③ Disaster monitoring and assessment

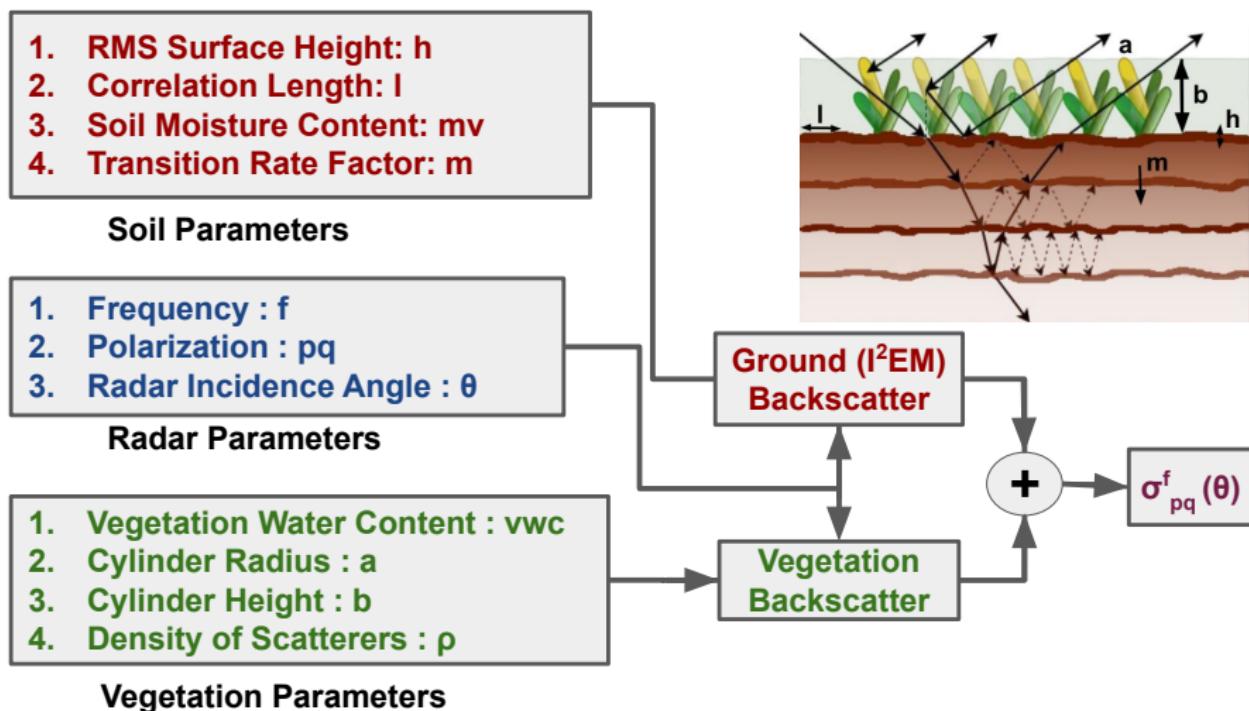


¹Credits : <https://nisar.jpl.nasa.gov/>

Forward Model - Schematic



Forward Model - Block Diagram



Heterogeneous Soil Moisture Profile

- IEM assumes the soil profile to be homogeneous²
- However soil moisture varies as a function of depth
- Need to model the soil profile as a multilayer dielectric surface

²A. K. Fung, Z. Li and K. S. Chen, "Backscattering from a randomly rough dielectric surface," in IEEE Transactions on Geoscience and Remote Sensing, 1992.

Heterogeneous Soil Moisture Profile

- IEM assumes the soil profile to be homogeneous²
- However soil moisture varies as a function of depth
- Need to model the soil profile as a multilayer dielectric surface

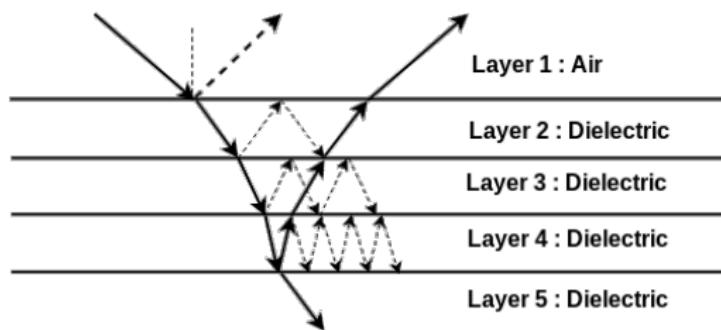


Figure: Multiple radar reflections from dielectric layers

²A. K. Fung, Z. Li and K. S. Chen, "Backscattering from a randomly rough dielectric surface," in IEEE Transactions on Geoscience and Remote Sensing, 1992.

Modeling Depth Dependent Moisture

Transitional Dielectric Profile³

$$\epsilon_r(z) = 1 + \frac{2(\epsilon_0 - 1)}{1 + e^{-mz}}$$

³A. K. Fung et al., "A modified IEM model for: scattering from soil surfaces with application to soil moisture sensing," IGARSS, 1996

Modeling Depth Dependent Moisture

Transitional Dielectric Profile³

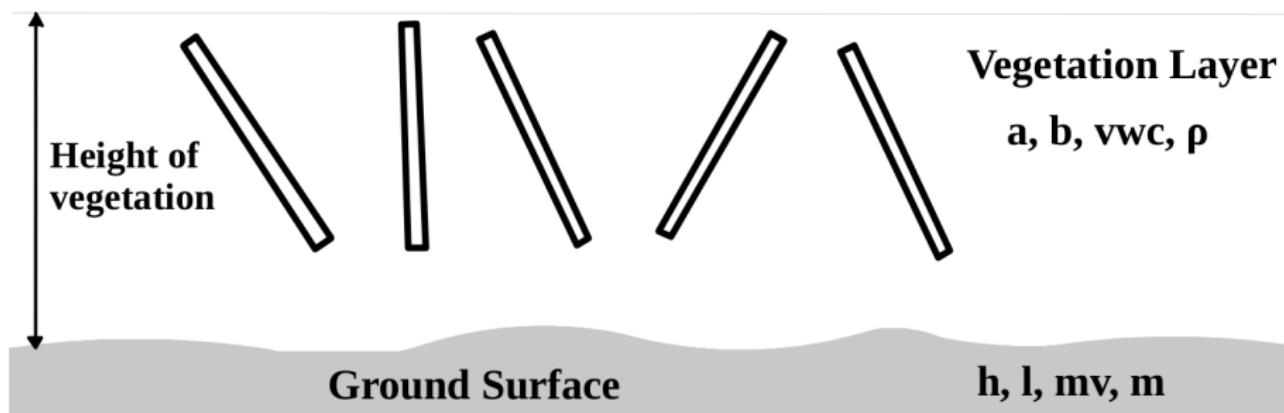
$$\epsilon_r(z) = 1 + \frac{2(\epsilon_0 - 1)}{1 + e^{-mz}}$$

- $m = 0$ corresponds to homogeneous soil profile
- Calculate effective reflection coefficient using Transfer Matrix Method
- Update the Fresnel reflectivities in the original IEM
- Obtain the new backscattering coefficient σ

³A. K. Fung et al., "A modified IEM model for: scattering from soil surfaces with application to soil moisture sensing," IGARSS, 1996

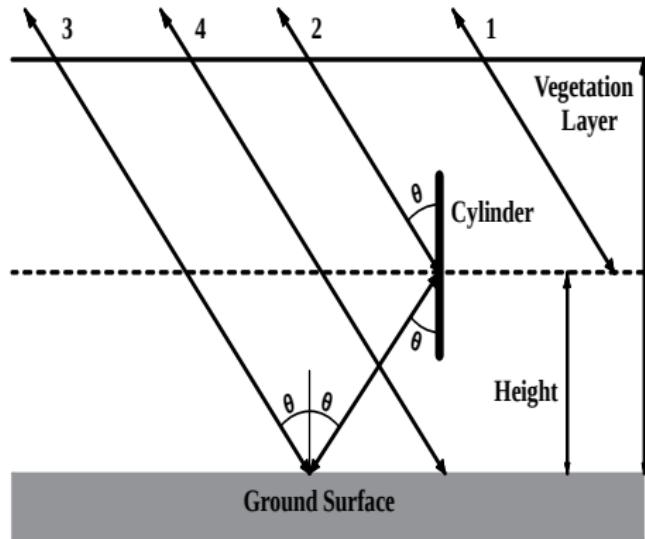
Soil moisture retrieval over vegetated terrain

- A single layer vegetation model
- Describes scattering from grasslands, pasture lands, etc.
- Spatial distribution of cylinders dictated by a pdf e.g. $\cos^2 \theta$



Single Layer Vegetation Model

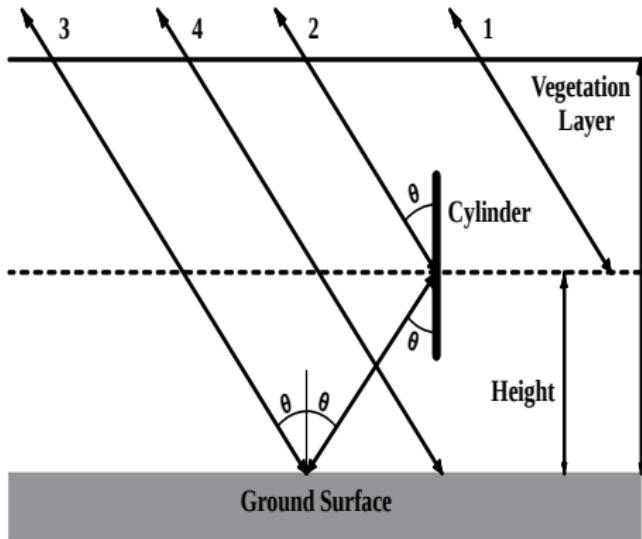
- ➊ Scattering from the Vegetation Layer (Path 1)
- ➋ Double Reflection Scattering (Paths 2 and 3)
- ➌ Backscatter from the Ground Surface (Path 4)



³van Zyl, Jakob J. Synthetic aperture radar polarimetry. Vol. 2. John Wiley and Sons, 2011

Single Layer Vegetation Model

- ➊ Scattering from the Vegetation Layer (Path 1)
- ➋ Double Reflection Scattering (Paths 2 and 3)
- ➌ Backscatter from the Ground Surface (Path 4)

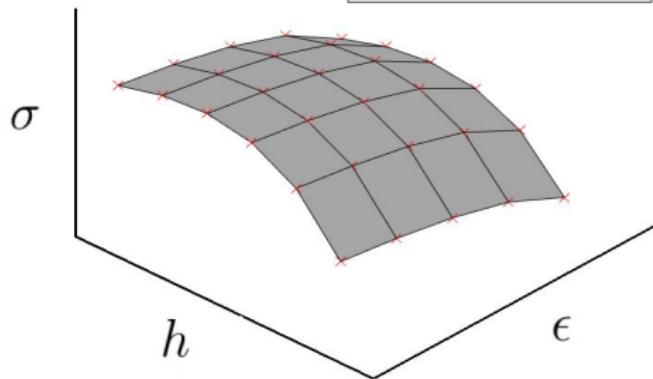
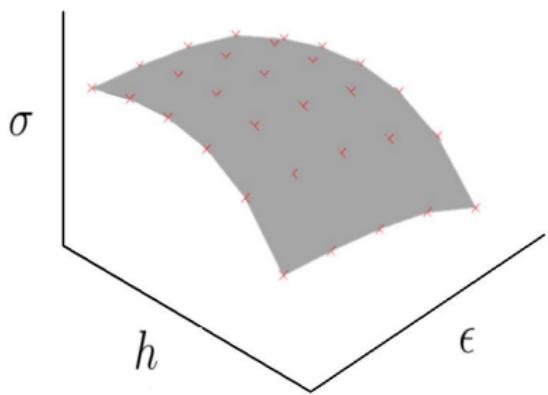


Backscatter Contributions from soil and vegetation

$$\sigma_{total} = \sigma_{veg}(vwc, a, b, \rho_s) + \tau^2 \sigma_{IEM}(h, l, \epsilon) + \sigma_{db}(vwc, a, b, \rho_s, h, l, \epsilon)$$

³van Zyl, Jakob J. Synthetic aperture radar polarimetry. Vol. 2. John Wiley and Sons, 2011

Sliced Regression Inversion Algorithm



Matrix Formulation - Forward Model

Linear Regression

$$\sigma = \beta_0 + \beta_1 h + \beta_2 I + \beta_3 m_v + \beta_4 m + \beta_5 vwc$$

Matrix Formulation - Forward Model

Linear Regression

$$\sigma = \beta_0 + \beta_1 h + \beta_2 l + \beta_3 m_v + \beta_4 m + \beta_5 vwc$$

$$\underbrace{\begin{bmatrix} \sigma_1^{hh,L} & \sigma_1^{vv,L} & \sigma_1^{hh,S} & \sigma_1^{vv,S} & \sigma_1^{hv,L} & \sigma_1^{hv,S} \\ \sigma_2^{hh,L} & \sigma_2^{vv,L} & \sigma_2^{hh,S} & \sigma_2^{vv,S} & \sigma_2^{hv,L} & \sigma_2^{hv,S} \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ \sigma_n^{hh,L} & \sigma_n^{vv,L} & \sigma_n^{hh,S} & \sigma_n^{vv,S} & \sigma_n^{hv,L} & \sigma_n^{hv,S} \end{bmatrix}}_{\mathbf{Y}} = \underbrace{\begin{bmatrix} 1 & h_1 & l_1 & mv_1 & m_1 & vwc_1 \\ 1 & h_2 & l_2 & mv_2 & m_2 & vwc_2 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 1 & h_n & l_n & mv_n & m_n & vwc_n \end{bmatrix}}_{\mathbf{X}} \underbrace{\begin{bmatrix} \beta_0^{hh,L} & \beta_0^{vv,L} & \dots & \beta_0^{hv,S} \\ \beta_1^{hh,L} & \beta_1^{vv,L} & \dots & \beta_1^{hv,S} \\ \vdots & \vdots & \ddots & \vdots \\ \beta_5^{hh,L} & \dots & \dots & \beta_5^{hv,S} \end{bmatrix}}_{\boldsymbol{\beta}}$$

Matrix Formulation - Inverse Model

Solve the least squares equation and find the bin with minimum error

$$\underset{x}{\text{minimize}} \quad ||\beta x - y||_2^2 \quad \text{subject to} \quad lb \leq x \leq ub \quad \text{for each bin}$$

Matrix Formulation - Inverse Model

Solve the least squares equation and find the bin with minimum error

$$\underset{x}{\text{minimize}} \quad ||\beta x - y||_2^2 \quad \text{subject to} \quad \mathbf{lb} \leq x \leq \mathbf{ub} \quad \text{for each bin}$$

$$\underbrace{\begin{bmatrix} \sigma^{hh,L} - \beta_0^{hh,L} \\ \sigma^{vv,L} - \beta_0^{vv,L} \\ \sigma^{hh,S} - \beta_0^{hh,S} \\ \sigma^{vv,S} - \beta_0^{vv,L} \\ \sigma^{hv,L} - \beta_0^{hv,L} \\ \sigma^{hv,S} - \beta_0^{hv,S} \end{bmatrix}}_y = \underbrace{\begin{bmatrix} \beta_1^{hh,L} & \beta_2^{hh,L} & \beta_3^{hh,L} & \beta_4^{hh,L} & \beta_5^{hh,L} \\ \beta_1^{vv,L} & \beta_2^{vv,L} & \beta_3^{vv,L} & \beta_4^{vv,L} & \beta_5^{vv,L} \\ \beta_1^{hh,S} & \beta_2^{hh,S} & \beta_3^{hh,S} & \beta_4^{hh,S} & \beta_5^{hh,S} \\ \beta_1^{vv,S} & \beta_2^{vv,S} & \beta_3^{vv,S} & \beta_4^{vv,S} & \beta_5^{vv,S} \\ \beta_1^{hv,L} & \beta_2^{hv,L} & \beta_3^{hv,L} & \beta_4^{hv,L} & \beta_5^{hv,L} \\ \beta_1^{hv,S} & \beta_2^{hv,S} & \beta_3^{hv,S} & \beta_4^{hv,S} & \beta_5^{hv,S} \end{bmatrix}}_\beta \underbrace{\begin{bmatrix} h \\ l \\ mv \\ m \\ vwc \end{bmatrix}}_x$$

Retrieval Results

- SR inversion performs better than SMART inverse model ⁴
Range : $m_v = [0.05, 0.4]$, $h = [0.3, 1.5]$

RMSE	m_v	h
SMART Inversion	0.07	0.25
Single band SR	0.05	0.19
Dual band SR	0.03	0.14

⁴Dubois, et. al. "Measuring soil moisture with imaging radars." IEEE Transactions on Geoscience and Remote Sensing (1995)

Retrieval Results

- SR inversion performs better than SMART inverse model ⁴
Range : $m_v = [0.05, 0.4]$, $h = [0.3, 1.5]$

RMSE	m_v	h
SMART Inversion	0.07	0.25
Single band SR	0.05	0.19
Dual band SR	0.03	0.14

- Retrieving moisture in presence of vegetation
Range : $m_v = [0.05, 0.4]$, $vwc = [0.1, 0.5]$

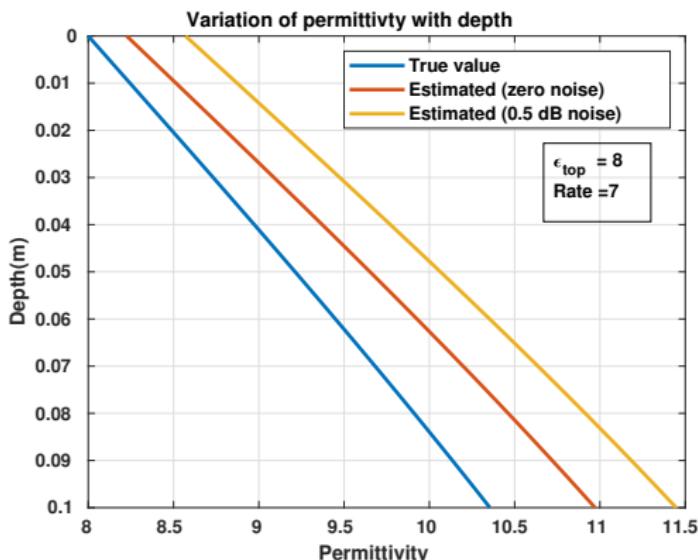
RMSE	m_v	vwc
Zero Noise	0.024	0.001
10 dB SNR	0.046	0.008

⁴Dubois, et. al. "Measuring soil moisture with imaging radars." IEEE Transactions on Geoscience and Remote Sensing (1995)

Retrieval results for depth dependent moisture

- Range : $\epsilon = [5, 15]$, $h = [0.3, 1.5]$

RMSE	ϵ	h
Zero Noise	1.07	0.03
10 dB SNR	1.13	0.11



Conclusion

- Sliced Regression Inversion - an algorithm rooted in electromagnetic theory
- Performs better than SMART Inversion algorithm
- Dual band works better than single band
- Retrieval of depth dependent moisture
- Retrieval of moisture from vegetation covered areas
- Future work
 - ① Testing on real datasets
 - ② Investigating the backscatter sensitivity to the soil and vegetation parameters